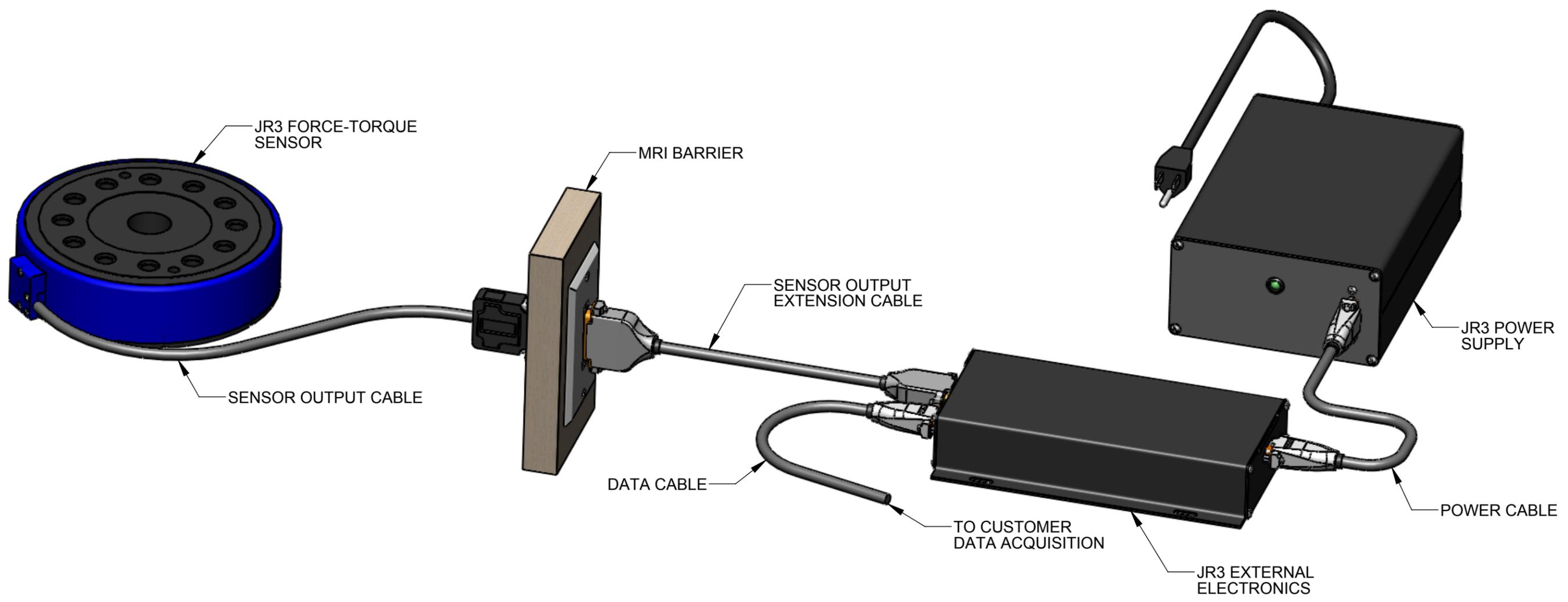


REVISIONS				
REV	DESCRIPTION	REV BY	DATE	APPROVED
-	INITIAL RELEASE	N/A	05-06-2015	G. SAKONA



NOTES:  
 1. DIAGRAM IS FOR REFERENCE, SOME DETAILS MAY BE DIFFERENT.

TITLE: JR3 FORCE-TORQUE SENSOR SYSTEM, MRI CONFIGURATION, ANALOG OUTPUT			
TOLERANCES: (UNLESS OTHERWISE NOTED)		DWG SIZE: B	DRAWN BY: K. NIELSEN
.XX = ±.010in	.XXX = ±.005in	SCALE: NOT TO SCALE	DWG NO: <b>9616</b>
.XXXX = ±.001in	ANGLES = ±0.1°		REV: -
<b>JR3, INC.</b> WOODLAND, CA 95776			SHEET 1 OF 1