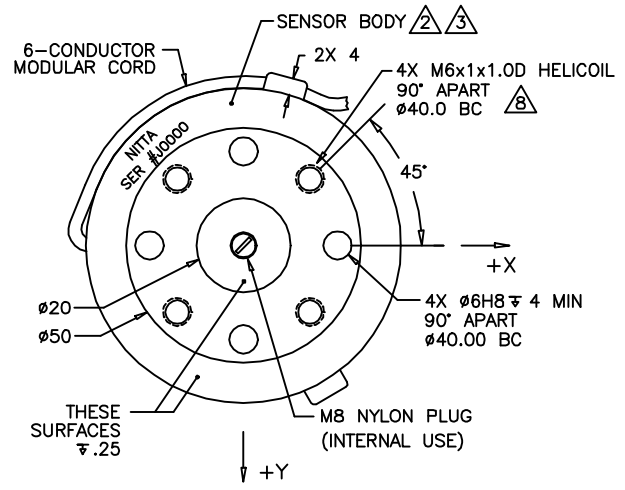
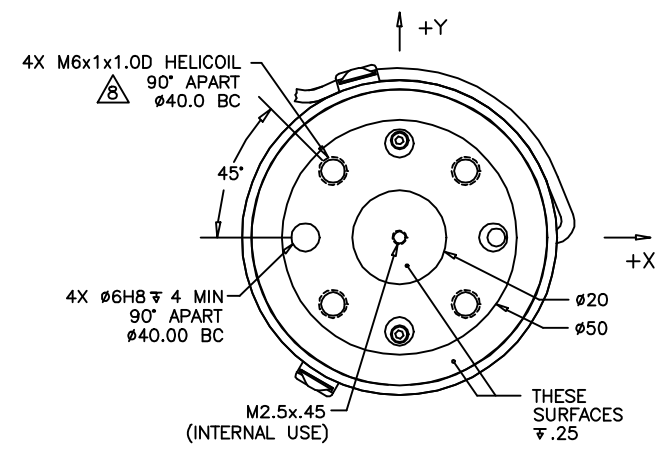
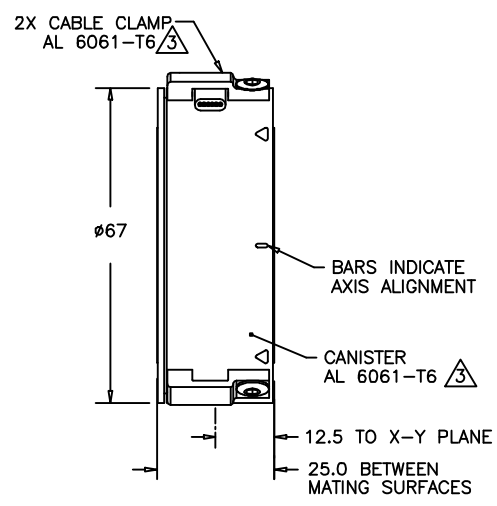


REVISIONS			
REV	DESCRIPTION	DATE	APPROVED
-	INITIAL RELEASE	05/01/01	G. SAKONA
A	SEE ECN E0673	05/18/01	G. SAKONA



TOOL VIEW



ROBOT VIEW

- NOTES:
- DIMENSIONS ARE IN MILLIMETERS UNLESS OTHERWISE NOTED.
 - SENSOR BODY MAY BE ALUMINUM (2024), STAINLESS STEEL (15-5PH), OR TITANIUM (Ti-6Al-4V).
 - ALUMINUM PARTS ARE ANODIZED, STAINLESS PARTS ELECTROPOLISHED, TITANIUM PARTS CHEMICALLY ETCHED.
 - STANDARD LOAD RATINGS INCLUDE: 63, 100, 125, 200N FOR ALUMINUM SENSORS, 160, 315, 350, 600N FOR STAINLESS STEEL SENSORS, 125, 250, 280, 450N FOR TITANIUM SENSORS,
 WHERE: FULL SCALE Fx, Fy = LOAD RATING
 FULL SCALE Fz = LOAD RATING * 2
 FULL SCALE Mx, My, Mz = LOAD RATING * NOMINAL DIAMETER (67mm)
 - AXES SHOWN ASSUME OPPOSITE SIDE HELD FIXED.
 - ROBOT VIEW IS RIGHT HAND RULE (JR3 STANDARD). THIS FORCES TOOL VIEW TO BE LEFT HAND RULE.
 - TORQUE MOUNTING SCREWS TO 14Nm (120inlb) IN 3 EQUAL STEPS, FOLLOWING AN ACBD SEQUENCE.
 - MAXIMUM ALLOWED SCREW PENETRATION INTO SENSOR IS 8mm.

TITLE: INTERFACE, 67M25 SENSOR, M40B, DUAL CABLE CLAMPS		
MAT'L: AS SHOWN	MODEL: 67M25A-M40BS 67M25S-M40BS 67M25T-M40BS	DRAWN: GCS
TOLERANCES: (UNLESS OTHERWISE NOTED) X = ±.25mm .X = ±.10mm .XX = ±.025mm ANGLES = ±0.1°		SCALE: 1/1 AND NOTED
		DWC SIZE: B
		DWG NO: 3844
		REV: A
JR3, INC. WOODLAND, CA 95776		
SHEET 1 OF 1		

AUTHORIZED COPY